

Tohoku University Research Program "Frontier Research in Duo" (FRiD)

Multi-Sensory Flexible Skin



Topic for FY2021

Magnetic foam for strain sensing – artificial touch sensor application





0.0

Frequency (Hz)

0.1

0.2

Force (N)

0.3

0.4

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3-times higher gauge factor

than piezoresistive transducer

2.0

2.5

3.0

3.5

4.0



Multi-Sensory Flexible Skin



Topic for FY2021

Robot hand demonstration and sensor readout circuit development







Human like robot hand demonstration with a developed form type tactile sensor and exoskeleton based controller



Sensor platform LSI including event-driven based response and serial bus communication





Inductance to voltage converter circuit for bridging a difference between our sensor platform LSI and developed sensor